



Edge TPU Coral Dev Board: A tutorial

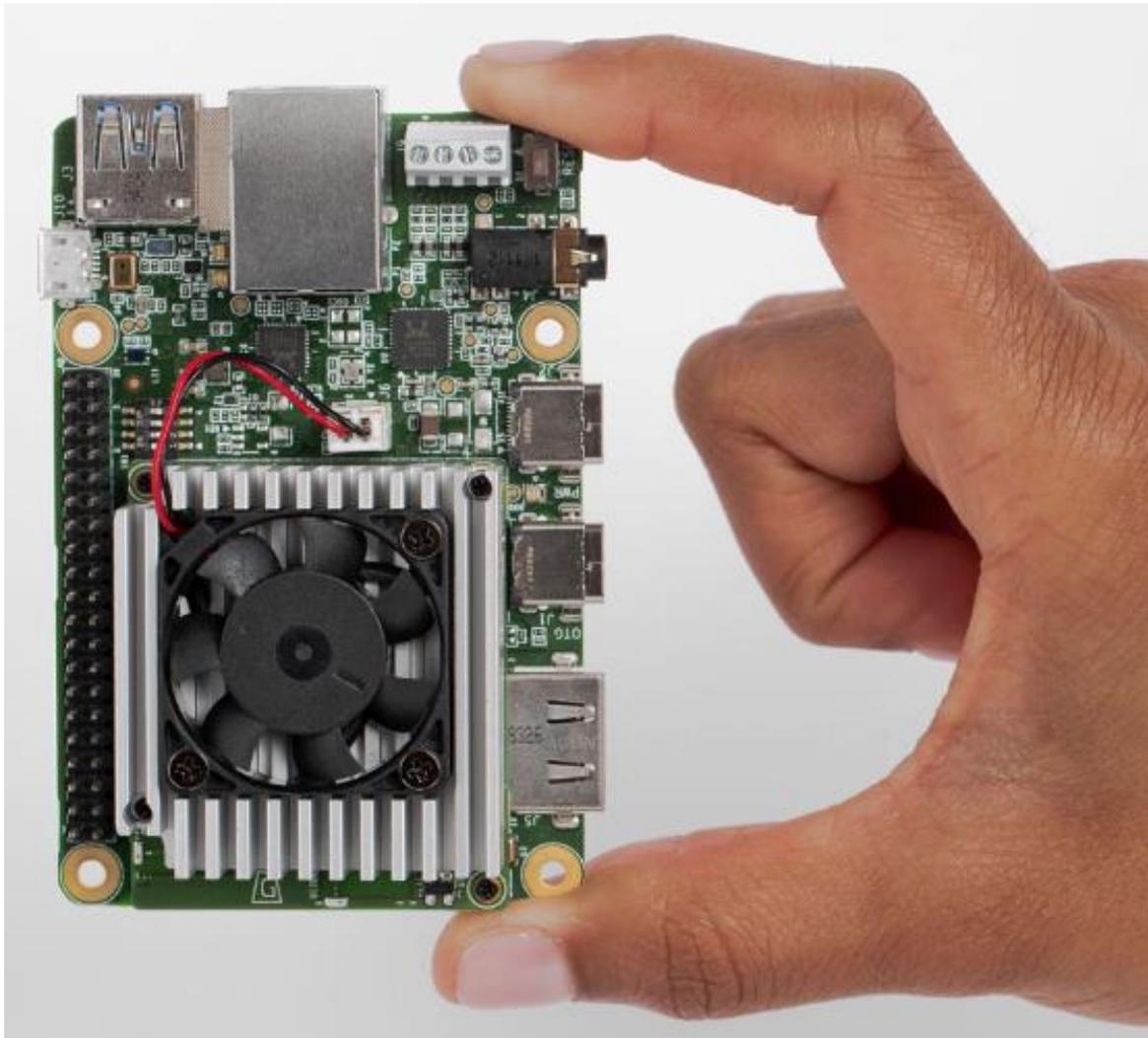
Adaptive Systems Laboratory
Division of Computer Engineering
School of Computer Science and Engineering
University of Aizu

Vu Huy The
d8182106@u-aizu.ac.jp
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Outline

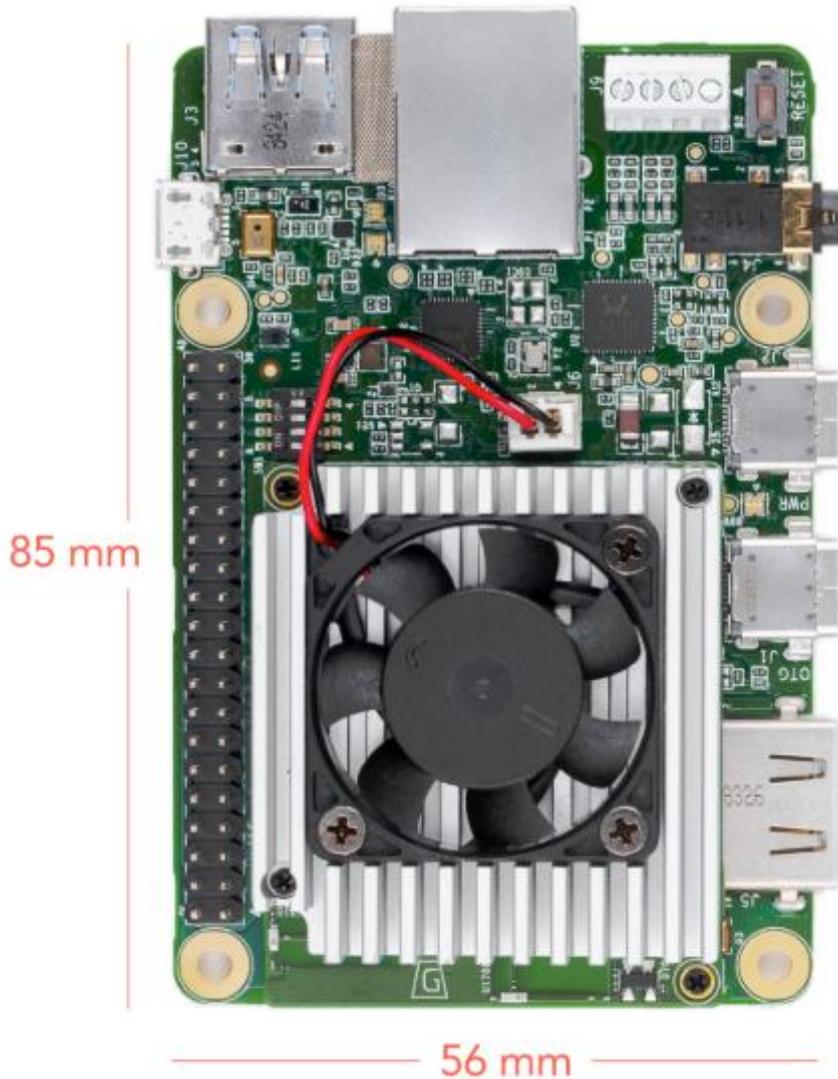
- Introduction and specification
- Required Hardware and tools
- Flash the board
- Run a model

Coral Dev Board



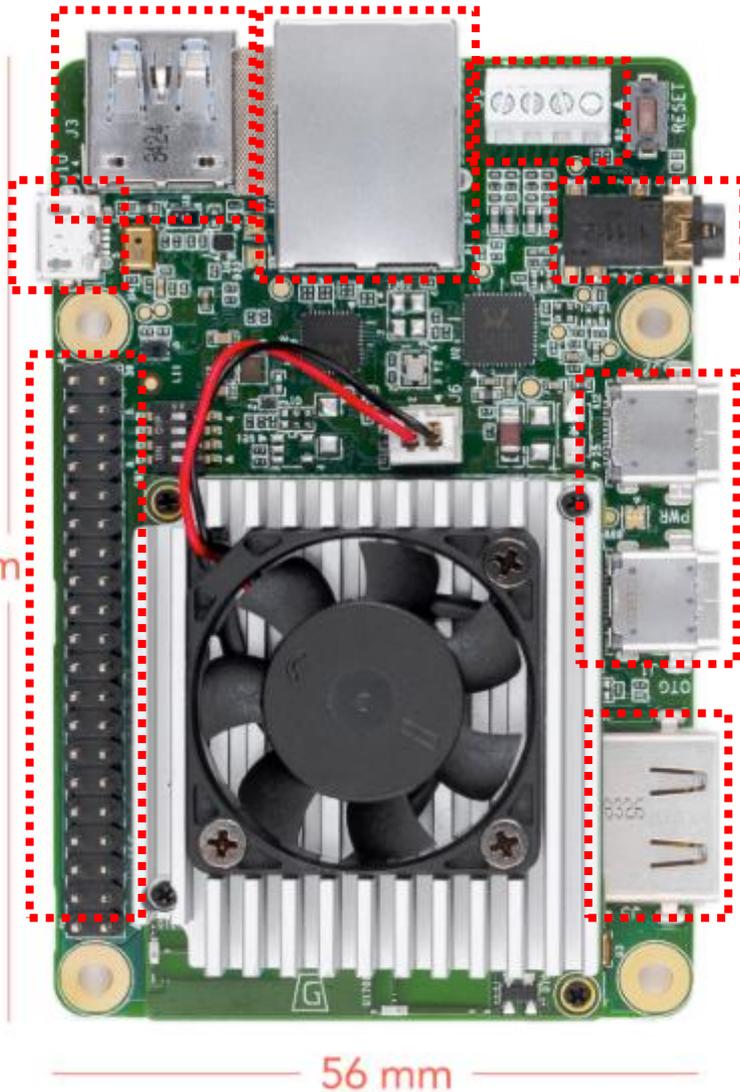
- ❑ The Coral Dev Board is a single-board computer with a removable system-on-module (SOM) that contains eMMC, SOC, wireless radios, and the Edge TPU.
- ❑ Accelerated ML; prototype internet-of-things (IOT) devices; embedded systems that demand fast on-device ML inferencing.

Board's Features (1/2)



- ❑ Edge TPU Module (SOM)
 - NXP i.MX 8M SOC (Quad-core Cortex-A53, plus Cortex-M4F)
 - Google Edge TPU ML accelerator coprocessor
 - Cryptographic coprocessor
 - Wi-Fi 2x2 MIMO (802.11b/g/n/ac 2.4/5GHz)
 - Bluetooth 4.1
 - 8GB eMMC
 - 1GB LPDDR4

Board's Features (2/2)



❑ USB connections

- USB Type-C power port (5V DC)
- USB 3.0 Type-C OTG port
- USB 3.0 Type-A host port
- USB 2.0 Micro-B serial console port

❑ Audio connections

- 3.5mm audio jack (CTIA compliant)
- Digital PDM microphone (x2)
- 2.54mm 4-pin terminal for stereo speakers

❑ Video connections

- HDMI 2.0a (full size)
- 39-pin FFC connector for MIPI DSI display (4-lane)
- 24-pin FFC connector for MIPI CSI-2 camera (4-lane)

❑ MicroSD card slot

❑ Gigabit Ethernet port

❑ 40-pin GPIO expansion header

❑ Supports Mendel Linux (derivative of Debian), Tensorflow Lite

Hardware and tools

□ Required hardware:

- Linux or Mac computer (referred to below as "host computer")
- USB-A to USB-microB cable (to connect your PC to the board's serial port)
- USB-A to USB-C cable (to connect your PC to the board's data port)
- 2 - 3A (5V) USB Type-C power supply (such as a phone charger)
- Ethernet cable or Wi-Fi connection

Hardware and tools

□ Tools:

- A serial console program: such as ***screen***, ***picocom***, or ***PuTTY*** (among many others), installed on host computer.

```
sudo apt-get install screen
```

- The **latest** ***fastboot*** tool.
 - Download [Android SDK Platform-tools](#)
 - Install:

```
mkdir -p ~/.local/bin
sudo mv ~/Downloads/platform-tools/fastboot ~/.local/bin/
```

- Verify:

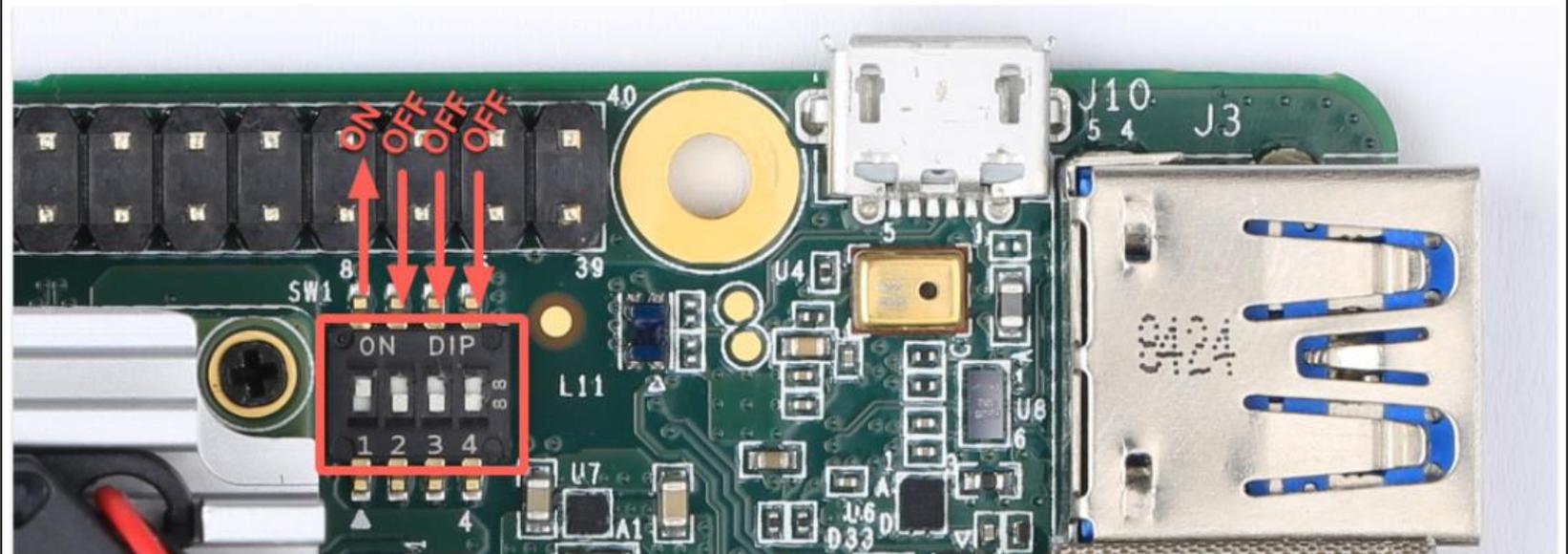
```
fastboot --version
```

Flash the board (1/8)

❑ Step 1: Switch to eMMC boot mode

- The board is completely unplugged (not powered and not connected to your computer).
- The boot mode switches are set to eMMC mode:

Boot mode	Switch 1	Switch 2	Switch 3	Switch 4
eMMC	ON	OFF	OFF	OFF



Flash the board (2/8)

❑ Step 2: Install the udev rule or driver on your host computer.

- This is required to communicate with the Dev Board over the serial console.
- *On Linux:*

```
sudo sh -c "echo 'SUBSYSTEM==\"usb\", ATTR{idVendor}==\"0525\", MODE==\"0664\", \
GROUP==\"plugdev\", TAG+=\"uaccess\"' >> /etc/udev/rules.d/65-edgetpu-board.rules"

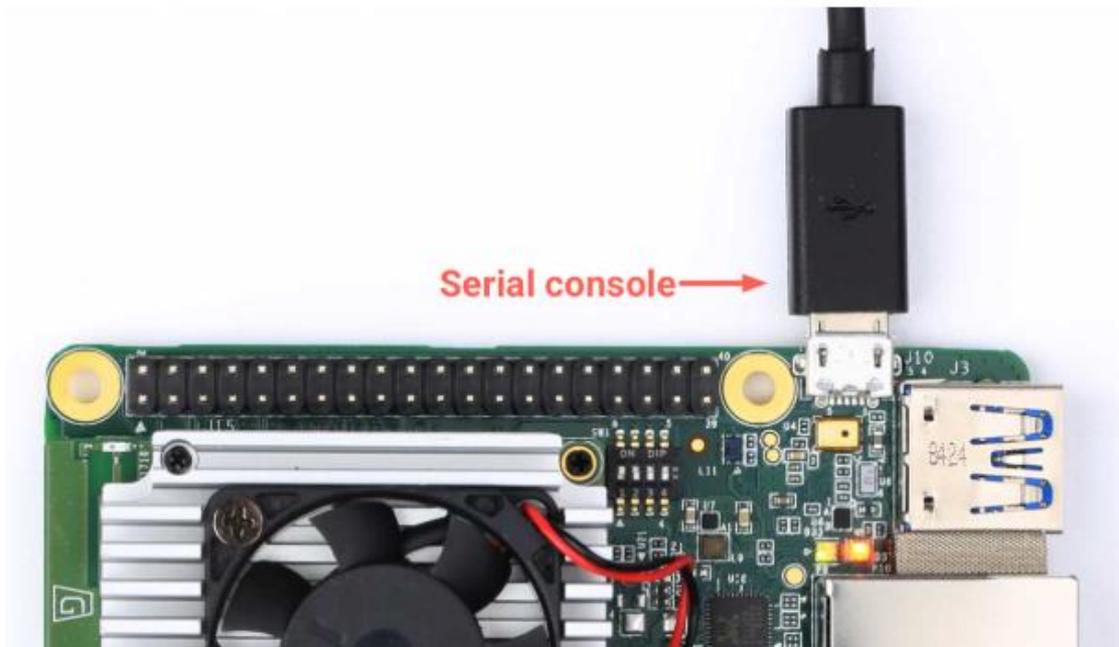
sudo udevadm control --reload-rules && udevadm trigger
```

- *On Mac:* [Install the CP210x USB to UART Bridge Virtual COM Port \(VCP\) driver for Mac.](#)

Flash the board (3/8)

□ Step 3: Connect to the serial console.

- USB-microB: host computer => to the serial console port on the board. The orange and green LEDs on the board should illuminate.



Flash the board (4/8)

□ Step 3: Connect to the serial console.

▪ *On Linux:*

- Determine the device filename

```
dmesg | grep ttyUSB
```

- You should see two results such as this:

```
[ 6437.706335] usb 2-13.1: cp210x converter now attached to ttyUSB0  
[ 6437.708049] usb 2-13.1: cp210x converter now attached to ttyUSB1
```

- Then use the name of the first filename listed as a cp210x converter to open the serial console connection

```
screen /dev/ttyUSB0 115200
```

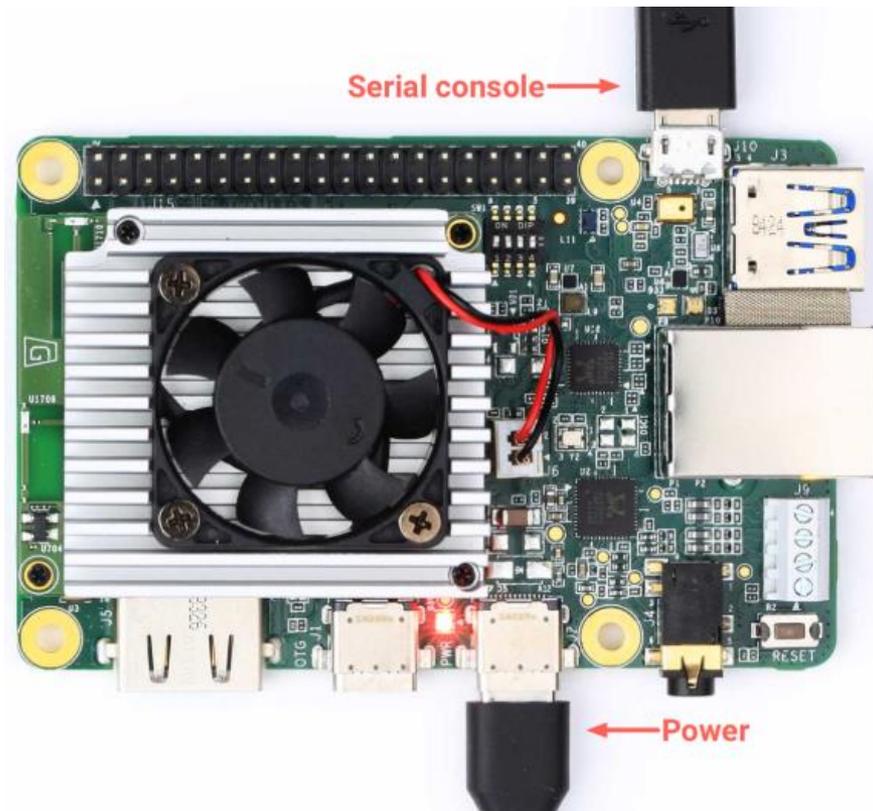
▪ *On Mac:*

```
screen /dev/cu.SLAB_USBtoUART 115200
```

Flash the board (5/8)

❑ Step 4: Power the board.

- Plug in your 2 - 3A power cable to the USB-C port labeled "PWR".
- Your serial console (the *screen* terminal) should arrive at the u-boot prompt. You should see a "Welcome" message
- **Caution:** Do not attempt to power the board by connecting it to your computer.
- **Help!** If you still don't see anything in the serial console screen, press Enter.



Flash the board (6/8)

□ Step 5: Start *fastboot*.

- In your serial console's u-boot prompt, execute the following:

```
fastboot 0
```

- The cursor should simply move to the next line. *Fastboot* is now waiting for the host to begin flashing a system image.

Flash the board (7/8)

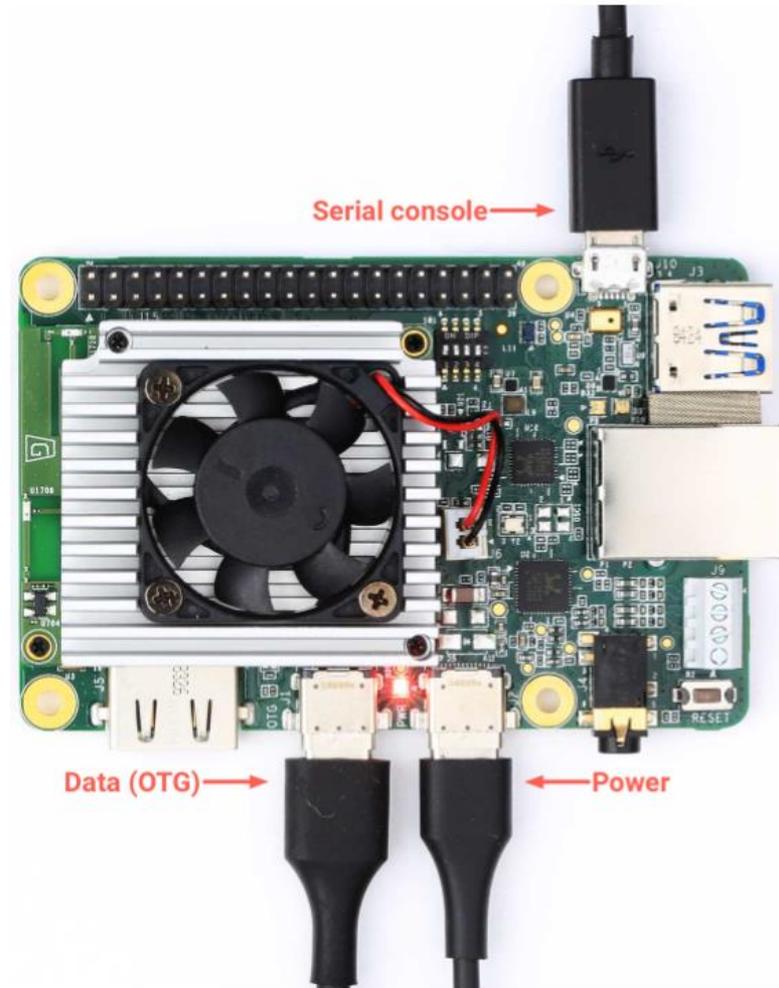
❑ Step 6: Connect to *fastboot* over USB.

- Use your USB-C cable to connect your host computer to the USB-C data port labeled "OTG" on the Dev Board.
- On host, open a new terminal

```
fastboot devices
```

- You should see a line printed like this:

```
1b0741d6f0609912    fastboot
```



Flash the board (8/8)

□ Step 7: Download and flash the system image.

- On host:

```
cd ~/Downloads

curl -O https://dl.google.com/coral/mendel/enterprise/mendel-enterprise-chef-13.zip

unzip mendel-enterprise-chef-13.zip \
&& cd mendel-enterprise-chef-13

bash flash.sh
```

- This starts the flashing process and you'll see various output.

Flash the board (8/)

□ Step 8: Login

- Switch back to the serial console to observe the flashing progress. It takes about 5 minutes to complete. When it's done, the system reboots and the console prompts you to login.

```
Login is mendel
```

```
Password is mendel
```

Mendel Development Tool: Install

- ❑ MDT is a command line tool that helps you perform tasks with connected Mendel devices, such as this Dev Board. For example, MDT can list connected devices, install Debian packages on a device, open a shell with a device, and more. And you'll need it in the next section to generate SSH keys.
- ❑ Install:

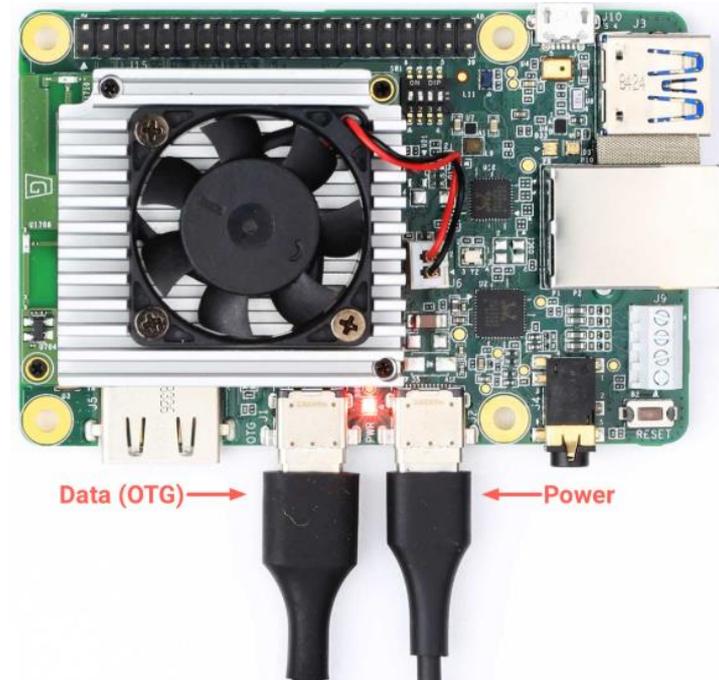
```
pip3 install --user mendel-development-tool
```

- Note:
 - The *--user* flag installs the mdt executable in your user directory.
 - On Linux, that's `~/.local/bin/`.
 - On a Mac, it's something like `/Users/yourname/Library/Python/3.7/bin/`.
 - If you remove that flag, it requires root access and will install at `/usr/local/bin`. So make sure that the appropriate path is in your PATH environment variable.

Mendel Development Tool: Connect

- ❑ Using the serial console was necessary only to enable fastboot. Now that you have the Mendel system on the board, you can unplug the microB USB cable and open a shell using MDT over the USB-C cable (see figure 5).
- ❑ Using MDT is just an easy way to generate an OpenSSH public/private key pair, push the public key onto the board, and then establish an SSH connection.
- ❑ To open the shell, run this command on your host computer:

```
mdt shell
```



Run a model: demo

On your desktop:

- For a video demo of the Edge TPU performance, run the following command from the Dev Board terminal:

```
edgetpu_demo --stream
```

- Then on your desktop (that's connected to the Dev Board)—if you're connected to the board using ssh over USB—open 192.168.100.2:4664 in a browser. If you're instead connected to the board by other means (such as SSH over LAN or with an Ethernet cable), type the appropriate IP address into your browser with port 4664.

Or if you have a monitor attached to the Dev Board, you can instead see the demo on that screen:

```
edgetpu_demo --device
```

Reference

[Google2019] Get started with the Dev Board, website: <https://coral.withgoogle.com/docs/dev-board/get-started/>, access date: May 10, 2019.